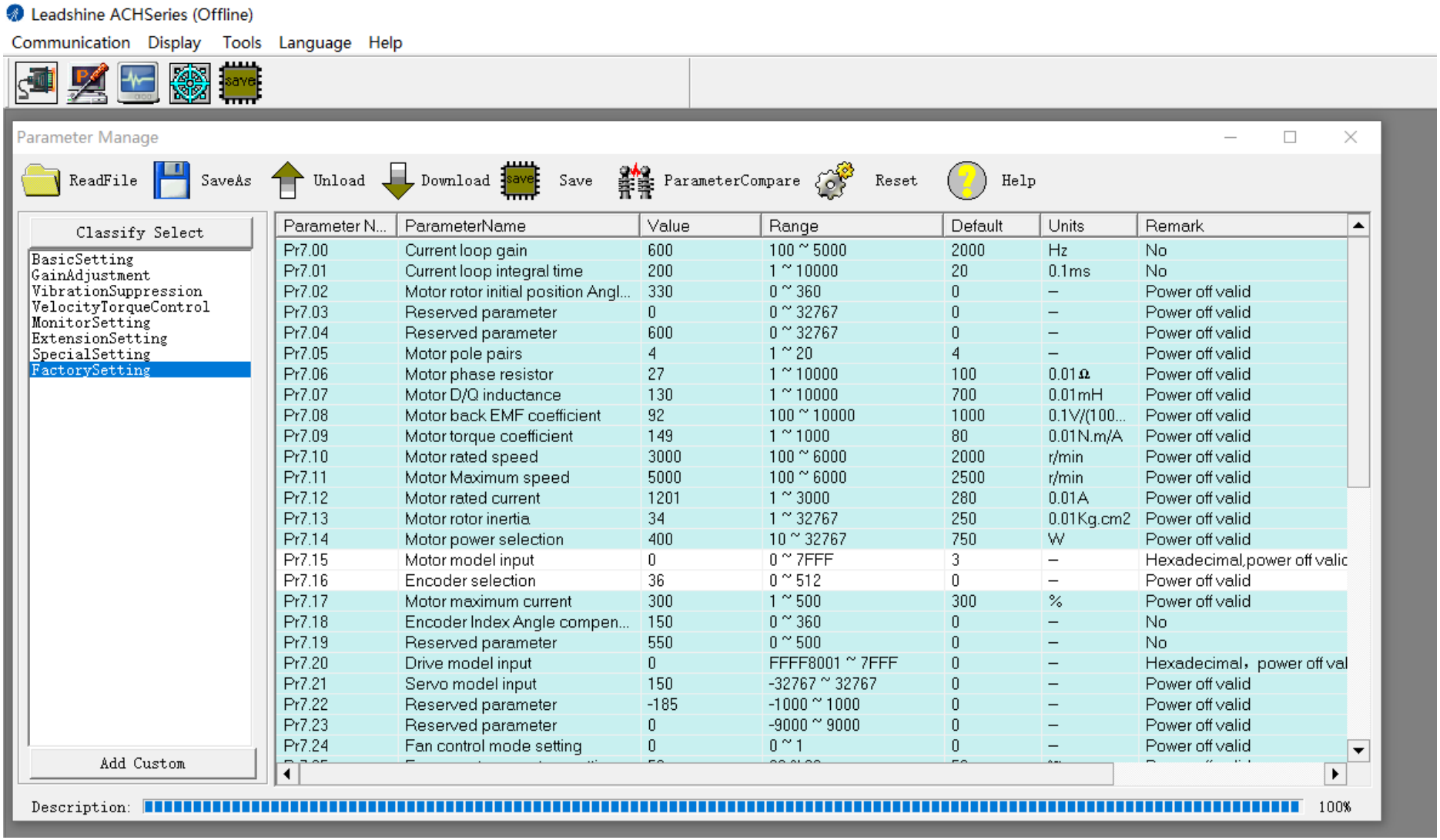
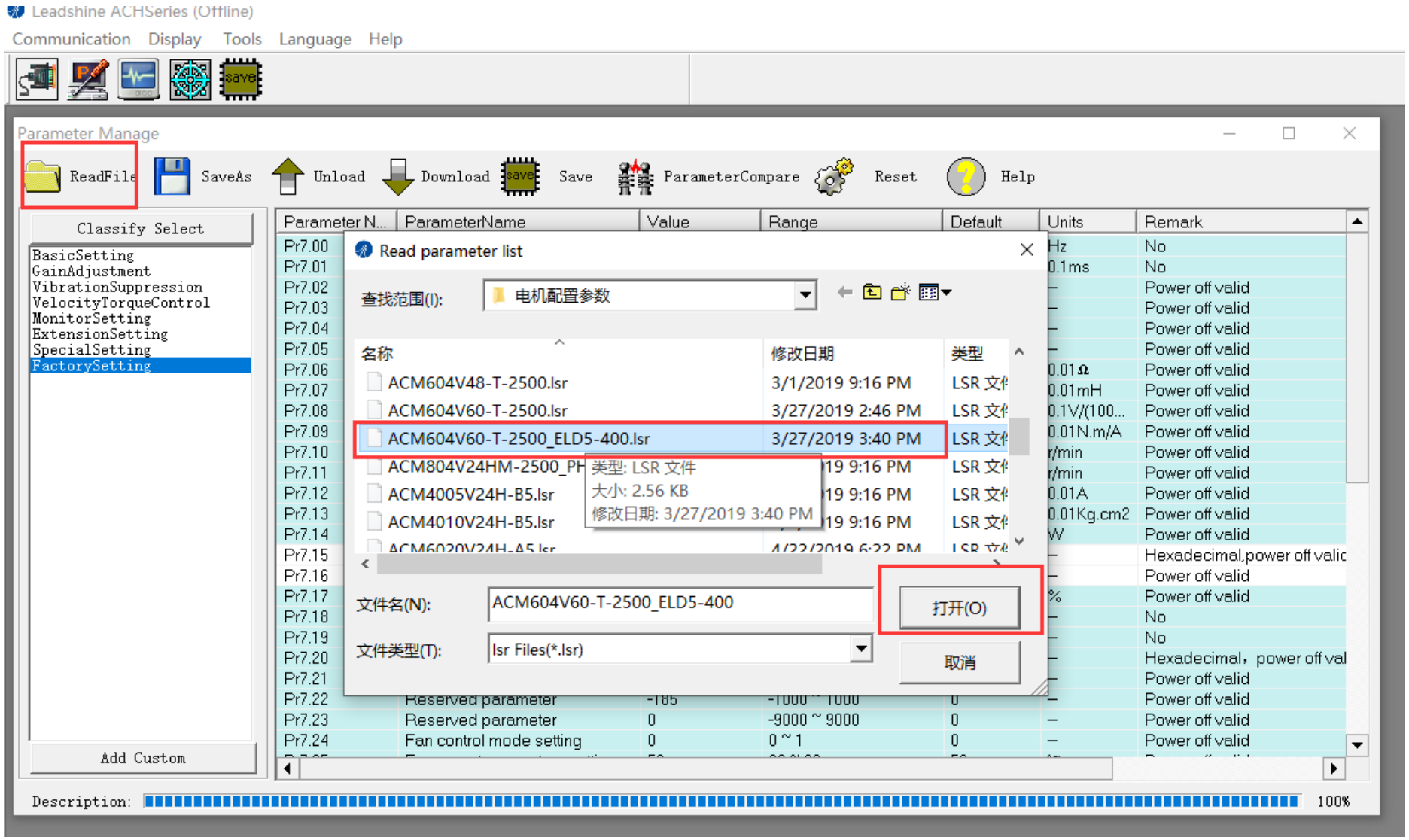
How to download the new lsr file to drive ELD5-400

1. Pls download the lsr setting file to your laptop .
2. Open protuner like this below :

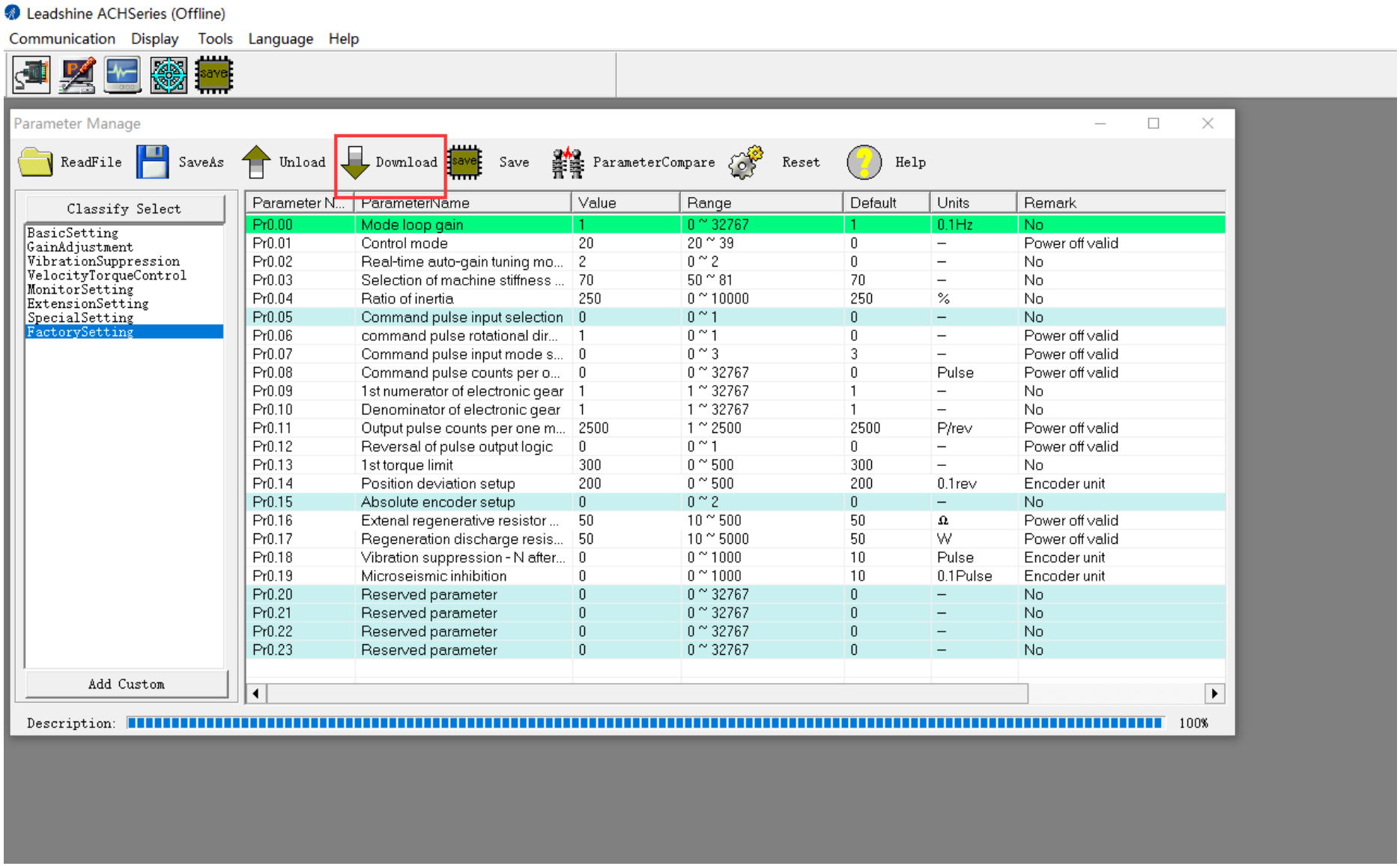


Parameter N...	ParameterName	Value	Range	Default	Units	Remark
Pr7.00	Current loop gain	600	100 ~ 5000	2000	Hz	No
Pr7.01	Current loop integral time	200	1 ~ 10000	20	0.1ms	No
Pr7.02	Motor rotor initial position Angl...	330	0 ~ 360	0	–	Power off valid
Pr7.03	Reserved parameter	0	0 ~ 32767	0	–	Power off valid
Pr7.04	Reserved parameter	600	0 ~ 32767	0	–	Power off valid
Pr7.05	Motor pole pairs	4	1 ~ 20	4	–	Power off valid
Pr7.06	Motor phase resistor	27	1 ~ 10000	100	0.01Ω	Power off valid
Pr7.07	Motor D/Q inductance	130	1 ~ 10000	700	0.01mH	Power off valid
Pr7.08	Motor back EMF coefficient	92	100 ~ 10000	1000	0.1V/(100...	Power off valid
Pr7.09	Motor torque coefficient	149	1 ~ 1000	80	0.01N.m/A	Power off valid
Pr7.10	Motor rated speed	3000	100 ~ 6000	2000	r/min	Power off valid
Pr7.11	Motor Maximum speed	5000	100 ~ 6000	2500	r/min	Power off valid
Pr7.12	Motor rated current	1201	1 ~ 3000	280	0.01A	Power off valid
Pr7.13	Motor rotor inertia	34	1 ~ 32767	250	0.01Kg.cm2	Power off valid
Pr7.14	Motor power selection	400	10 ~ 32767	750	W	Power off valid
Pr7.15	Motor model input	0	0 ~ 7FFF	3	–	Hexadecimal,power off valic
Pr7.16	Encoder selection	36	0 ~ 512	0	–	Power off valid
Pr7.17	Motor maximum current	300	1 ~ 500	300	%	Power off valid
Pr7.18	Encoder Index Angle compen...	150	0 ~ 360	0	–	No
Pr7.19	Reserved parameter	550	0 ~ 500	0	–	No
Pr7.20	Drive model input	0	FFFF8001 ~ 7FFF	0	–	Hexadecimal，power off val
Pr7.21	Servo model input	150	-32767 ~ 32767	0	–	Power off valid
Pr7.22	Reserved parameter	-185	-1000 ~ 1000	0	–	Power off valid
Pr7.23	Reserved parameter	0	-9000 ~ 9000	0	–	Power off valid
Pr7.24	Fan control mode setting	0	0 ~ 1	0	–	Power off valid

3. Click “readfile” : , then find the file from your laptop like below :

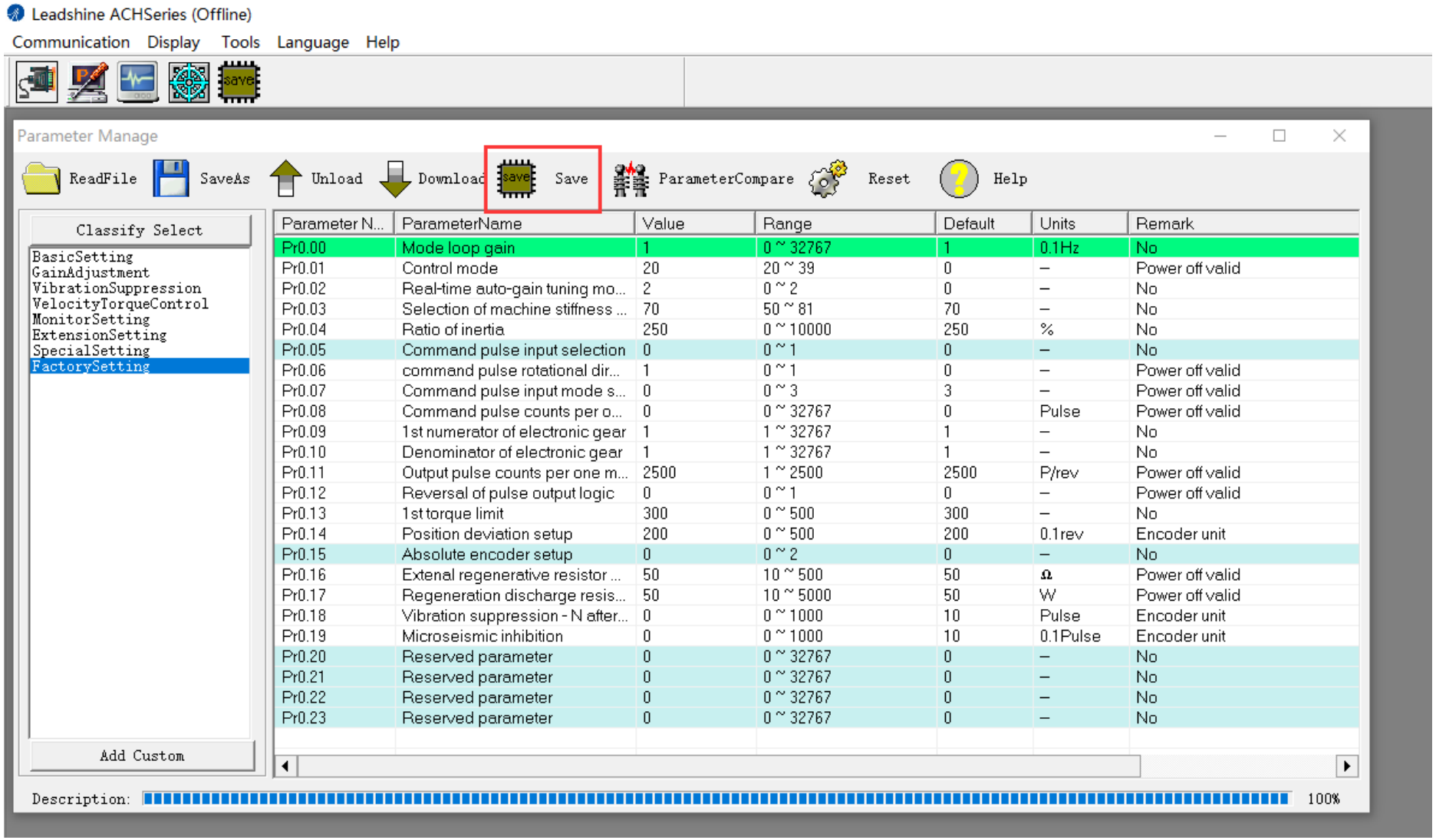


4. Then click “download”



Parameter N...	ParameterName	Value	Range	Default	Units	Remark
Pr0.00	Mode loop gain	1	0 ~ 32767	1	0.1Hz	No
Pr0.01	Control mode	20	20 ~ 39	0	–	Power off valid
Pr0.02	Real-time auto-gain tuning mo...	2	0 ~ 2	0	–	No
Pr0.03	Selection of machine stiffness ...	70	50 ~ 81	70	–	No
Pr0.04	Ratio of inertia	250	0 ~ 10000	250	%	No
Pr0.05	Command pulse input selection	0	0 ~ 1	0	–	No
Pr0.06	command pulse rotational dir...	1	0 ~ 1	0	–	Power off valid
Pr0.07	Command pulse input mode s...	0	0 ~ 3	3	–	Power off valid
Pr0.08	Command pulse counts per o...	0	0 ~ 32767	0	Pulse	Power off valid
Pr0.09	1st numerator of electronic gear	1	1 ~ 32767	1	–	No
Pr0.10	Denominator of electronic gear	1	1 ~ 32767	1	–	No
Pr0.11	Output pulse counts per one m...	2500	1 ~ 2500	2500	P/rev	Power off valid
Pr0.12	Reversal of pulse output logic	0	0 ~ 1	0	–	Power off valid
Pr0.13	1st torque limit	300	0 ~ 500	300	–	No
Pr0.14	Position deviation setup	200	0 ~ 500	200	0.1rev	Encoder unit
Pr0.15	Absolute encoder setup	0	0 ~ 2	0	–	No
Pr0.16	Extenal regenerative resistor ...	50	10 ~ 500	50	Ω	Power off valid
Pr0.17	Regeneration discharge resis...	50	10 ~ 5000	50	W	Power off valid
Pr0.18	Vibration suppression - N after...	0	0 ~ 1000	10	Pulse	Encoder unit
Pr0.19	Microseismic inhibition	0	0 ~ 1000	10	0.1Pulse	Encoder unit
Pr0.20	Reserved parameter	0	0 ~ 32767	0	–	No
Pr0.21	Reserved parameter	0	0 ~ 32767	0	–	No
Pr0.22	Reserved parameter	0	0 ~ 32767	0	–	No
Pr0.23	Reserved parameter	0	0 ~ 32767	0	–	No

5. Then click “save” :



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Pr0.23	Reserved parameter	0	0 ~ 32767	0	–	No

6. Then the setting file of drive has been covered with this new lsr file , then pls restart the power , then the setting will be suitable for your application .